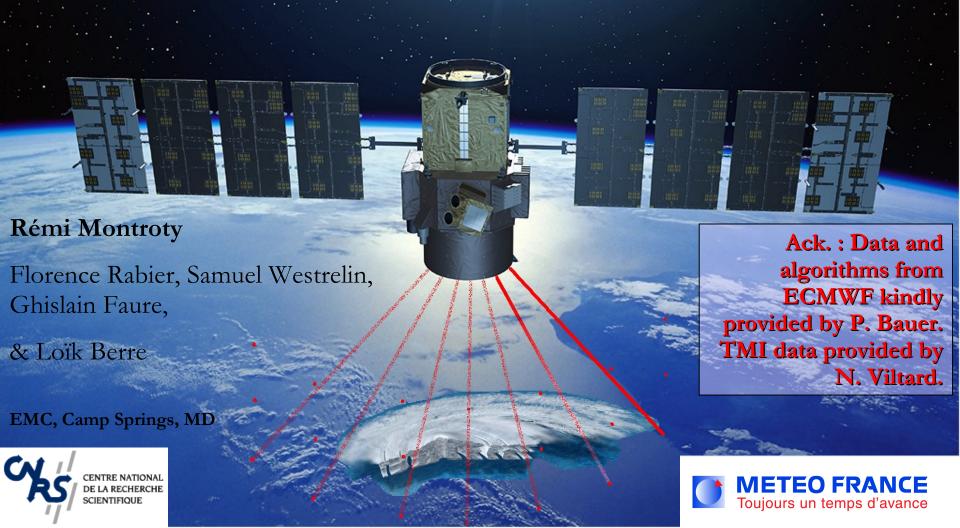
Impact of rain-affected microwave data assimilation on the analyses and forecasts of tropical cyclones



Outline

- I. Assimilating rain-affected SSM/I data and its impact on analyses & forecasts of TCs.
- II. Effects on downscaling to 4 km with AROME
- III. Diagnosing the flow-dependent variability of background errors
- IV. Impacts of those filtered errors on TC forecasting
- V. Conclusions



PART I:

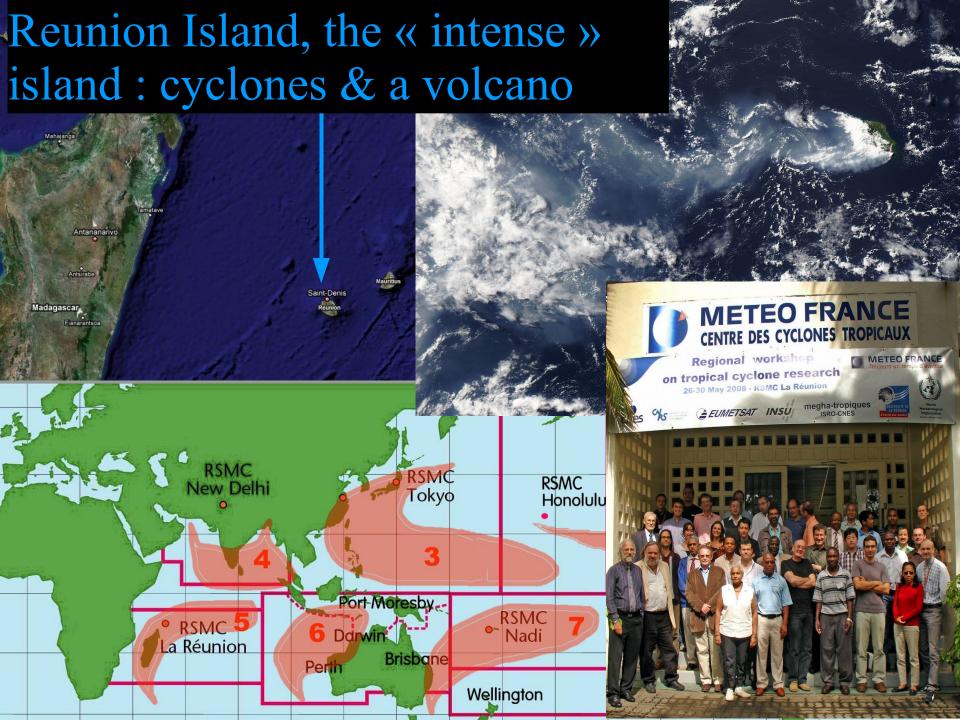
Assimilating rain-affected SSM/I data and its impact on analyses & forecasts of TCs.



A quick introduction

- La Réunion (french overseas department) is the official Regional Specialized Meteorological Center for Tropical Cyclone (TC) Watch, under the WMO's supervision.
- This thesis work was funded in order to support the operational need of a hi-res model (ALADIN) and to investigate possible ways to improve TC forecasts.

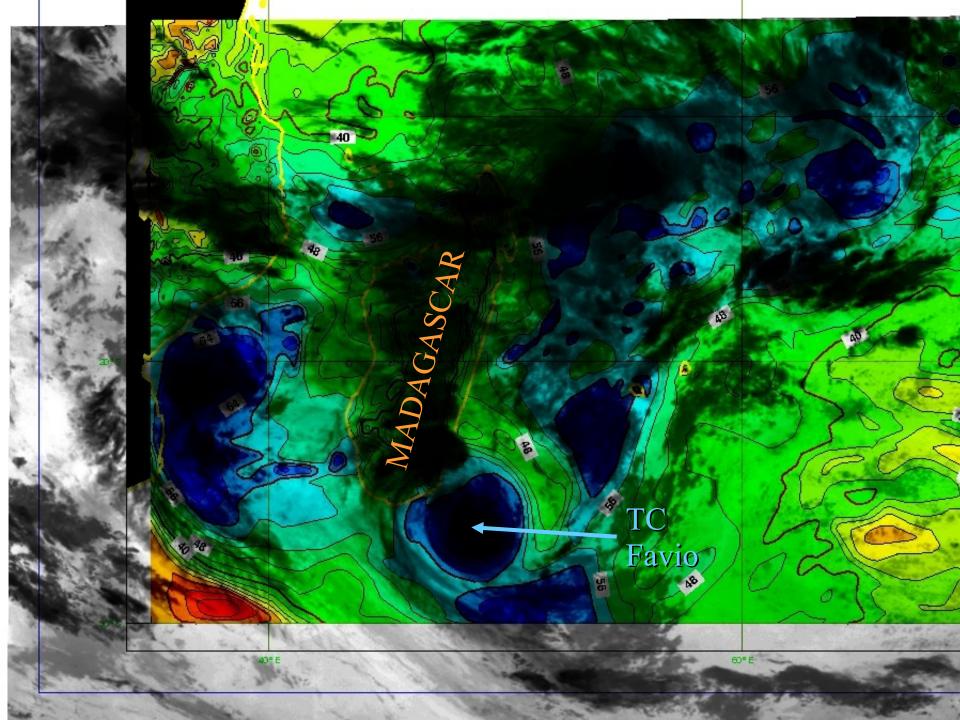




Motivation for this study

- NWP, and more specifically TC forecasting, is highly dependent on satellite observations
- These observations are usually not assimilated in cloudy and/or rainy conditions NCEP!
- Assimilation of rainy satellite radiances proves very costly (complex obs operators)

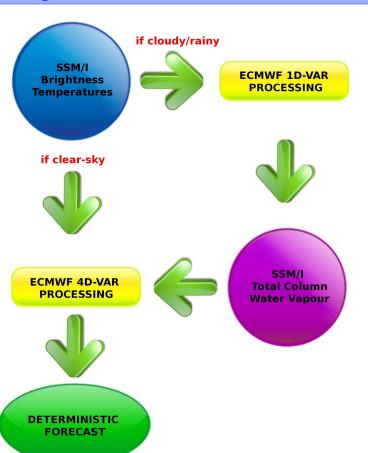




Methodology (1/3): Rainy SSM/I at ECMWF

The characterization of the cloudy/rainy condition is purely observation-based. Namely:

- If TB_{37H} - TB_{37V} < 40 K, the pixel is considered rainy.
- If LWP> 0.01 kg.m⁻², the pixel is considered cloudy; with



UNREAD. V-H??

LWP = $A_0 + A_1 * log(280-TB_{22V}) - A_2 * log(280-TB_{37H})$



Methodology (2/3): Retrieving the algorithm



Goal: Find a simple, statistical approach to link satellite radiances to the TCWV













- One algorithm per SSM/I satellite
- Learning period from Nov 27, 2006 until Feb 11, 2007. Area is the SWIO.
- 250000 to 350000 points
- 3 TC and 1 Tropical Storm sampled



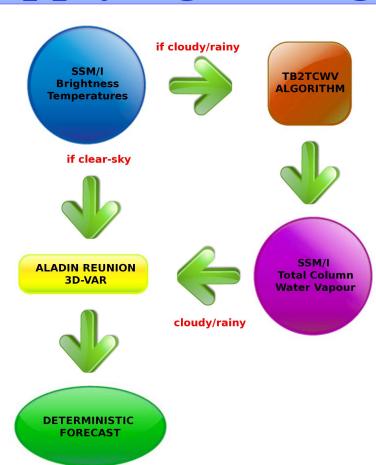
ightharpoonup Std dev $< 2.2 \text{ kg/m}^2$

Correlation > 0.985

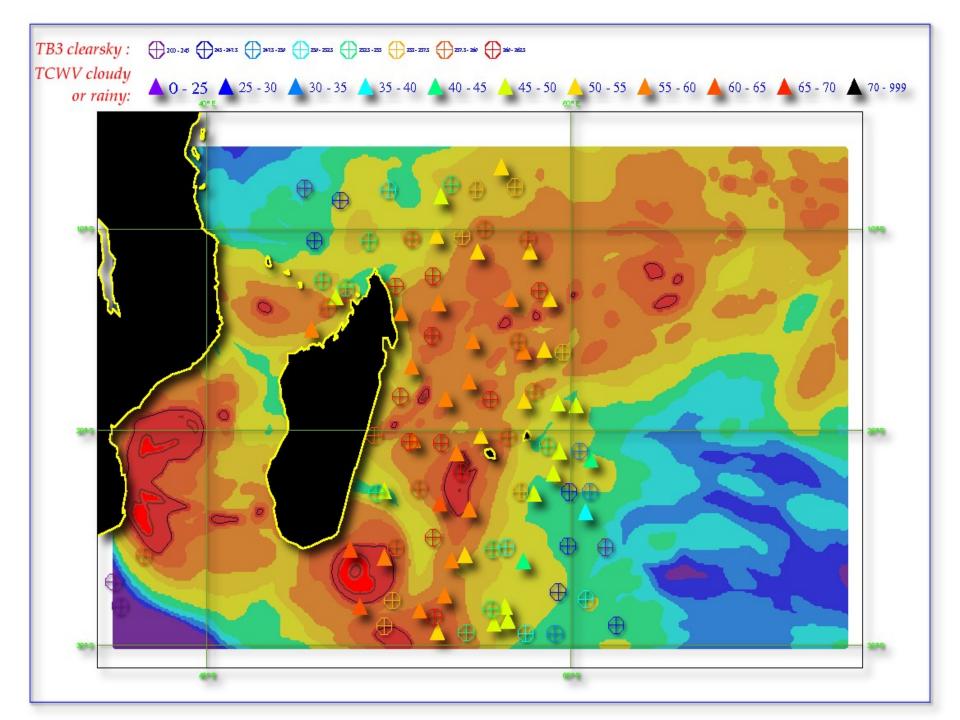


Methodology (3/3): Applying the algorithm

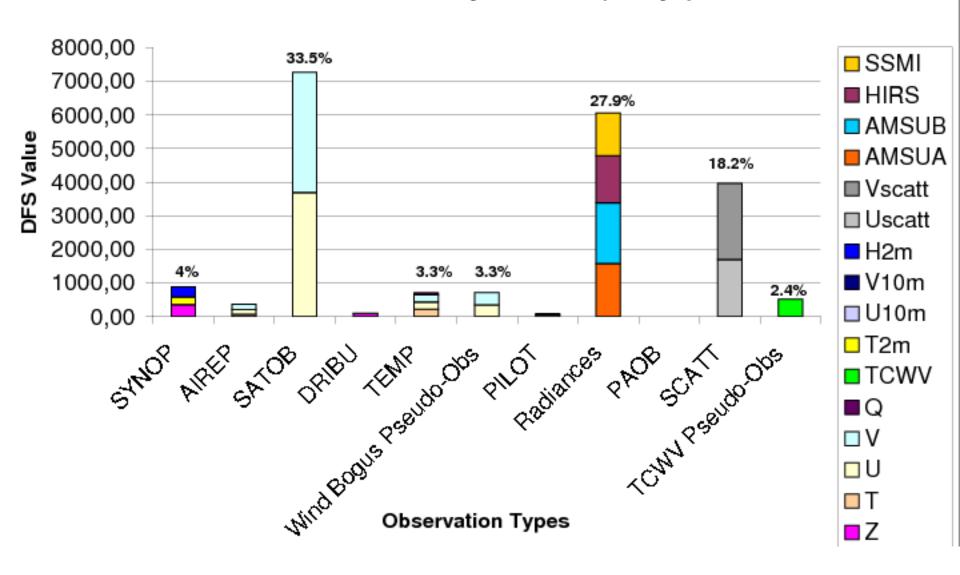
- The obtained TCWV is then assimilated in the ALADIN Reunion model (10km resolution, covers the SWIO)
- A 3D wind bogus following the UKMO technique (Heming, 1995) is used for cyclonic cases
- Several experiments
 were ran with the
 combination of TCWV
 and the 3D wind bogus







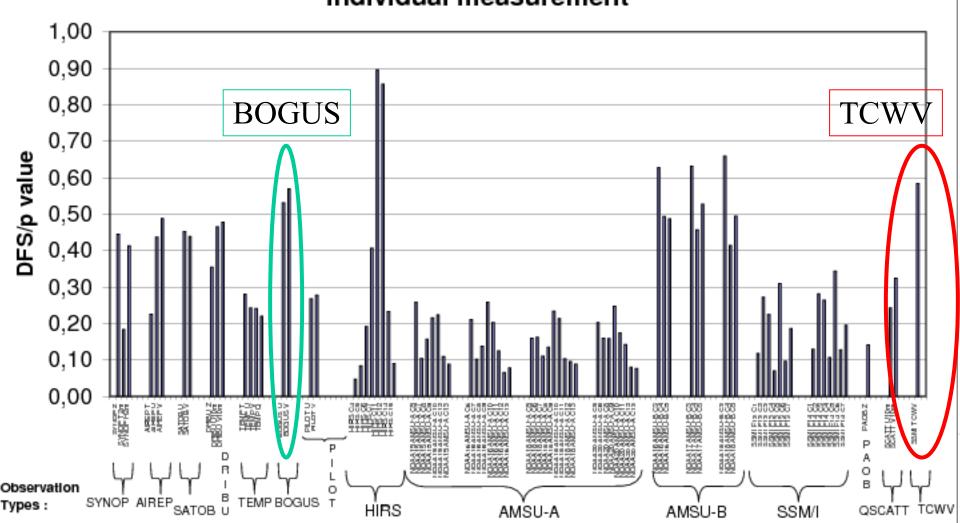
DFS over 16 analysis times (4 days)



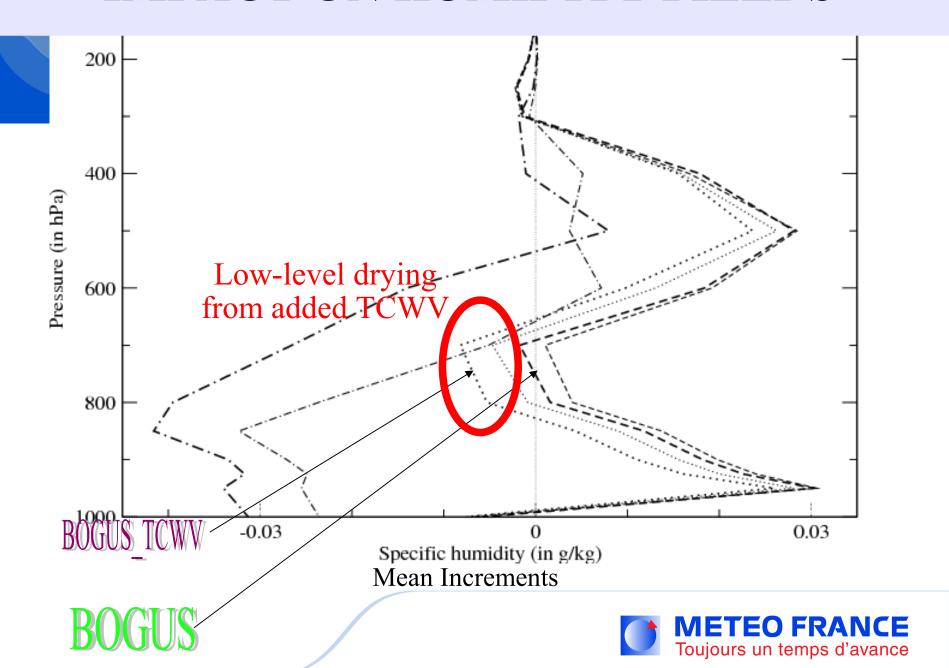


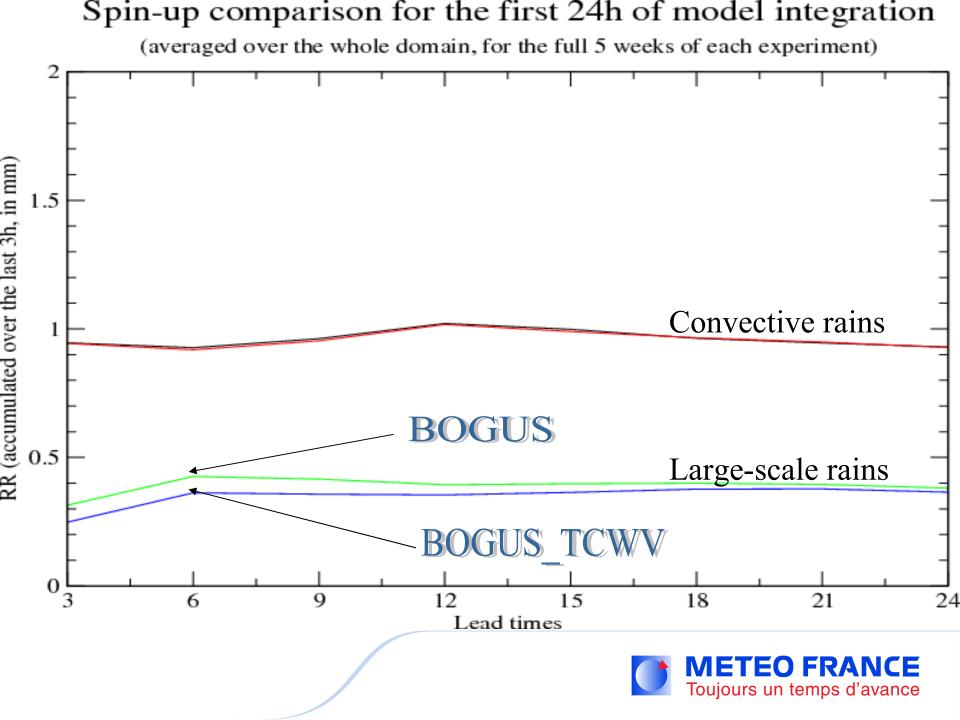
OBSERVATIONAL IMPACTS ON THE 3DVar ANALYSES

DFS/p : information content of each obstype and individual measurement



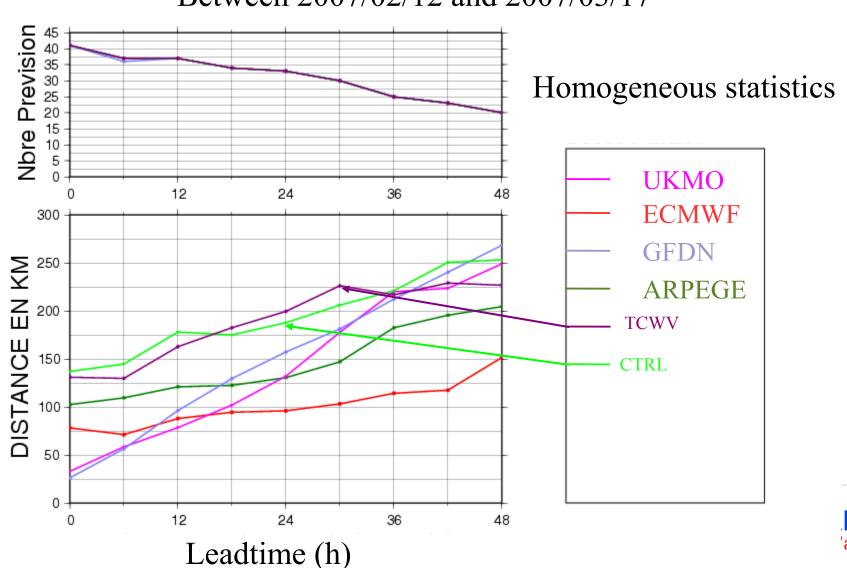
IMPACT ON HUMIDITY FIELDS





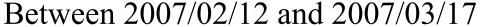
5-WEEK STATISTICS IN TERMS OF TRACK ERROR

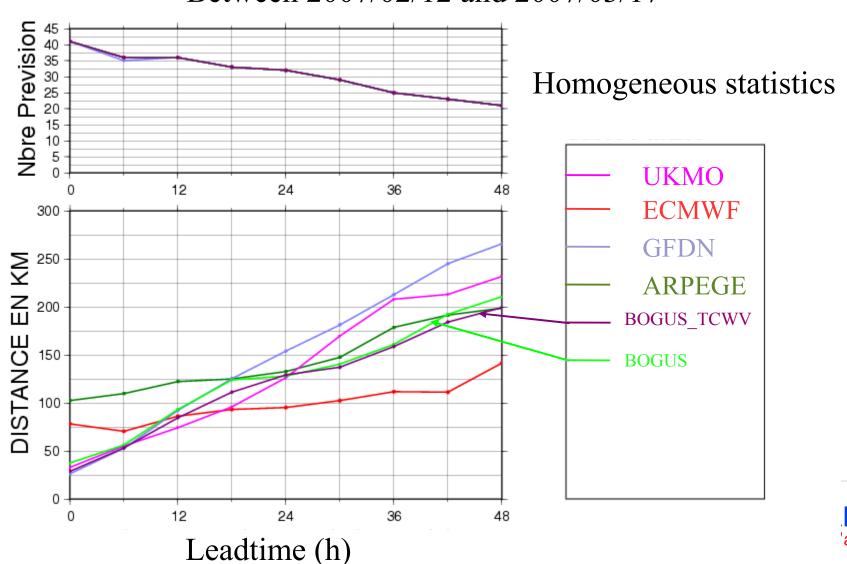
Between 2007/02/12 and 2007/03/17



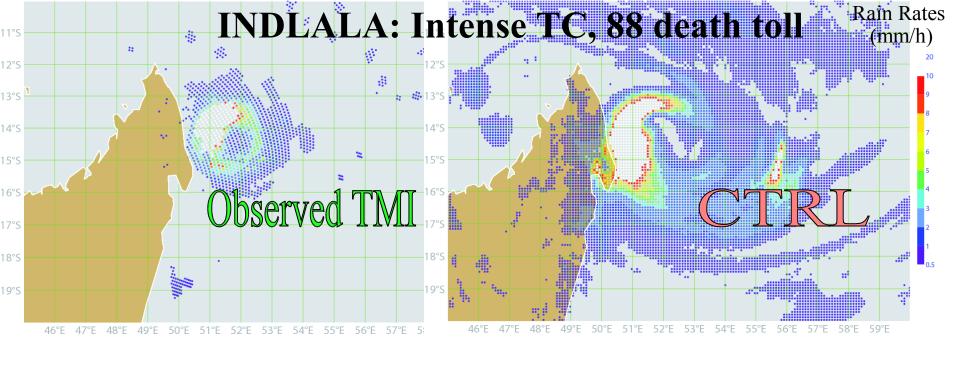


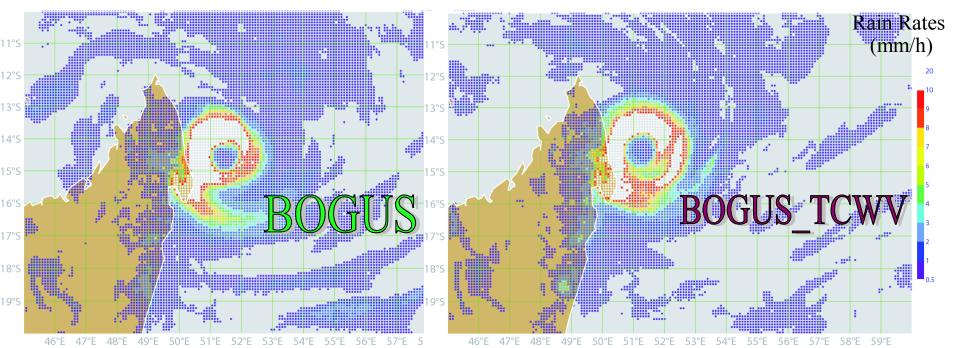
5-WEEK STATISTICS IN TERMS OF TRACK ERROR











Conclusions on Part I:

- This technique works and is definitely beneficial for the model: TCWV data assimilation helps constrain the analysis in cloudy/rainy conditions and leads to more realistic TC features, and to a better depiction of tropospheric humidity content (not shown).
- Possible expansion of the method to other satellites and other basins is to be investigated
- Up to 100% more SSM/I data points are gained in previously unsampled areas
- All these results are coming out soon in QJRMS (paper accepted)



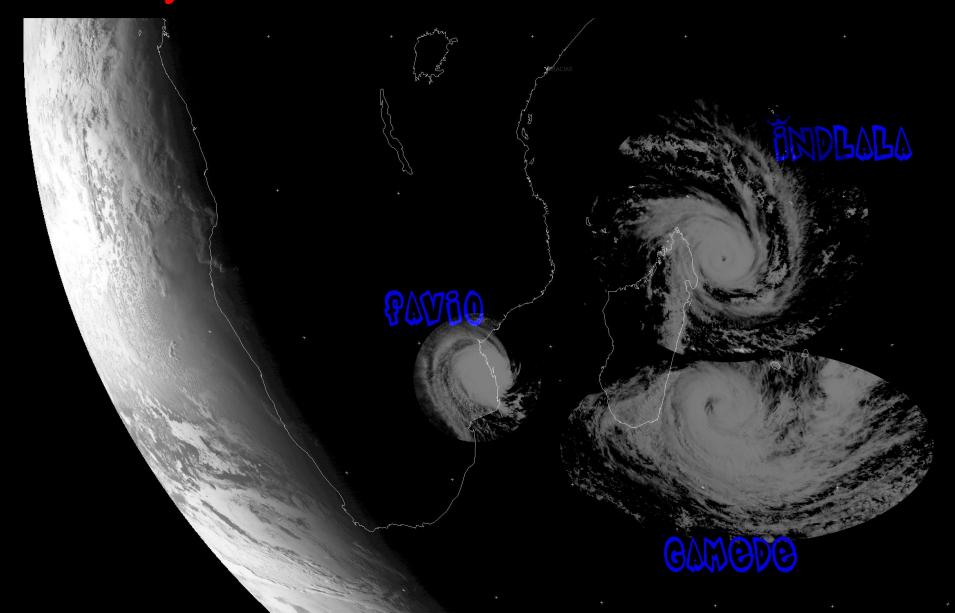
PART II: Effects on downscaling to 4 km with AROME

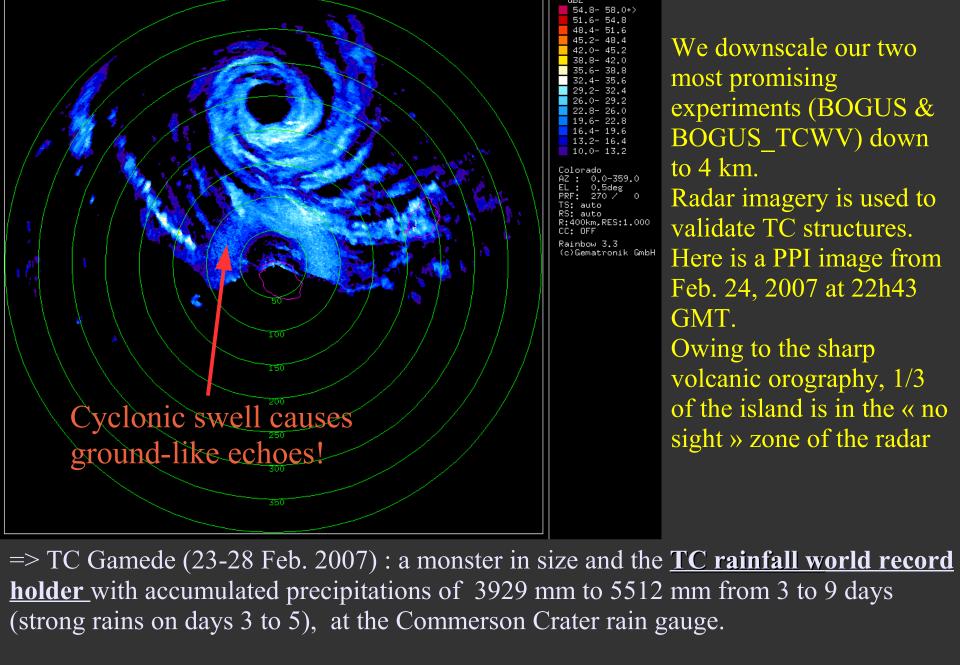


AROME

- AROME is the future weather forecast model of Météo-France, with non-hydrostatic dynamics, 2.5 km resolution and a sophisticated physical package with an explicit microphysical scheme, ICE3.
- Based on the physics developed for the LES model MESO-NH; built on ALADIN-NH dynamical core (bi-Fourier, spectral lam)
- Reproduces accurately deep convective events
- AROME France is now assimilating radar reflectivities
- AROME Reunion was implemented during my stay at Reunion Island in order to test its impact on TC forecast and sensitive weather that can occur on very small spatial scales

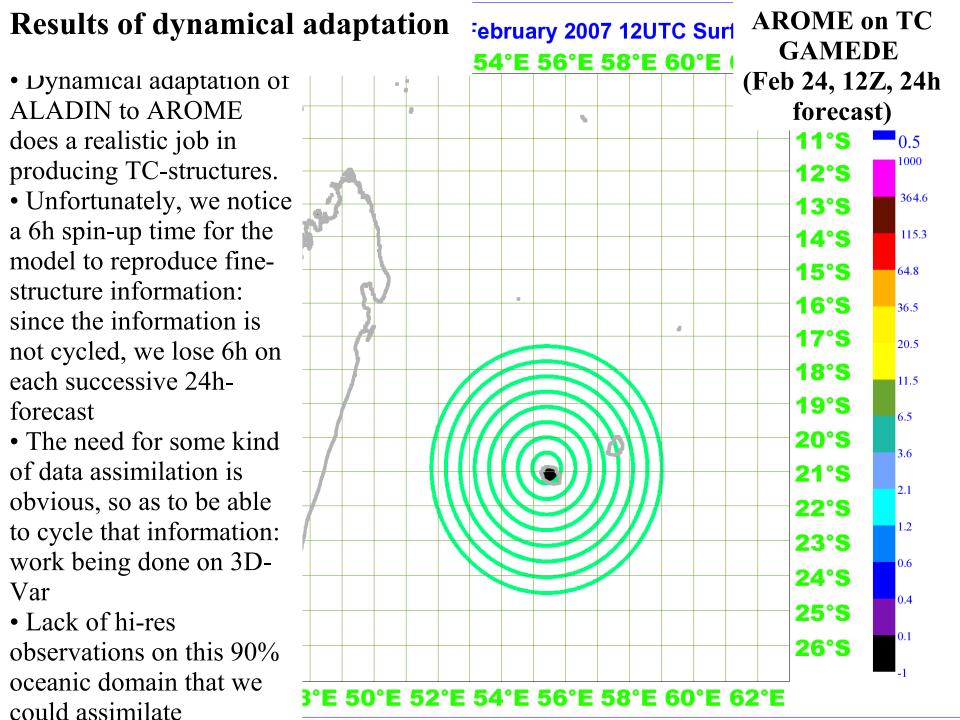
The three cyclones studied in ALADIN for the cyclonic season 2006/2007 of SWIO.

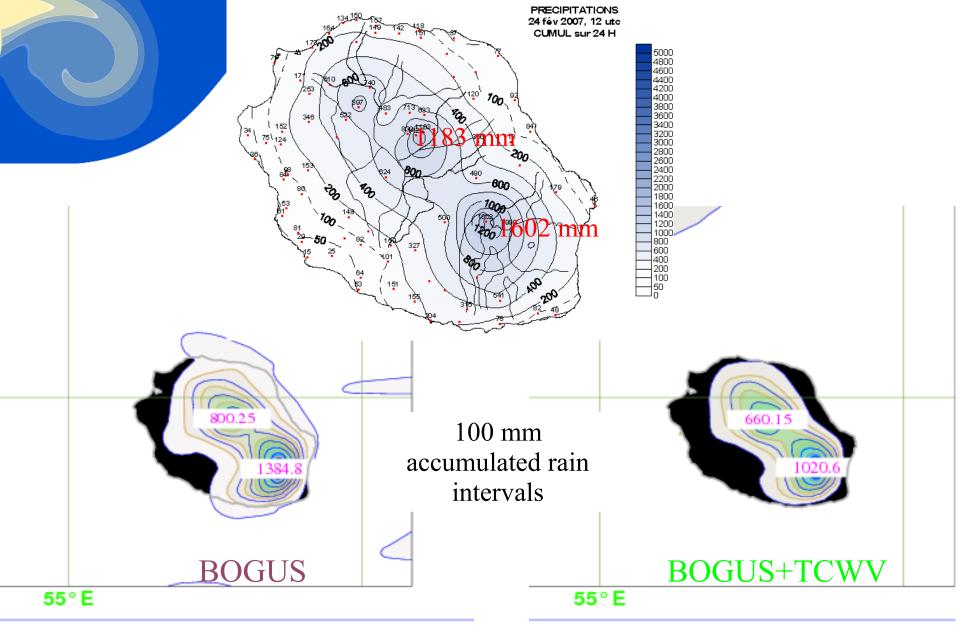




2007022422435230.ppz

Range: 400.0 km





=> The low-level drying results in less intense accumulated precipitations but the overall spatial distribution of precip enveloppes is better with TCWV.

PART III:

Diagnosing the flow-dependent variability of background errors

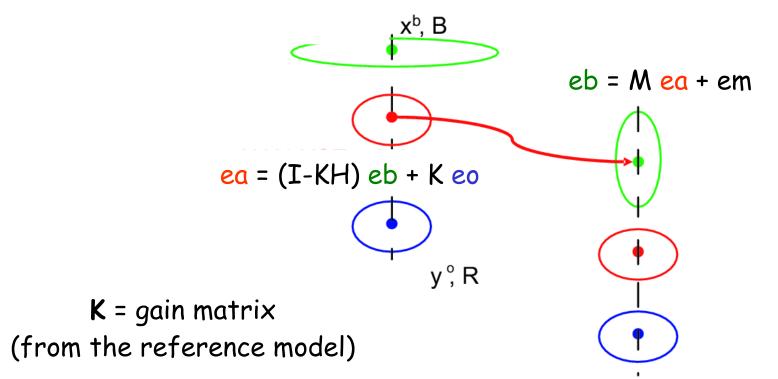


Ensemble assimilation: background errors « of the day »

Gérald Desroziers, Loïk Berre, Laure Raynaud, Olivier Pannekoucke, Bernard Chapnik,
Simona Stefanescu, Benedikt Strajnar, Rachida El Ouaraini, Pierre Brousseau, Rémi Montroty
Eric Sevault



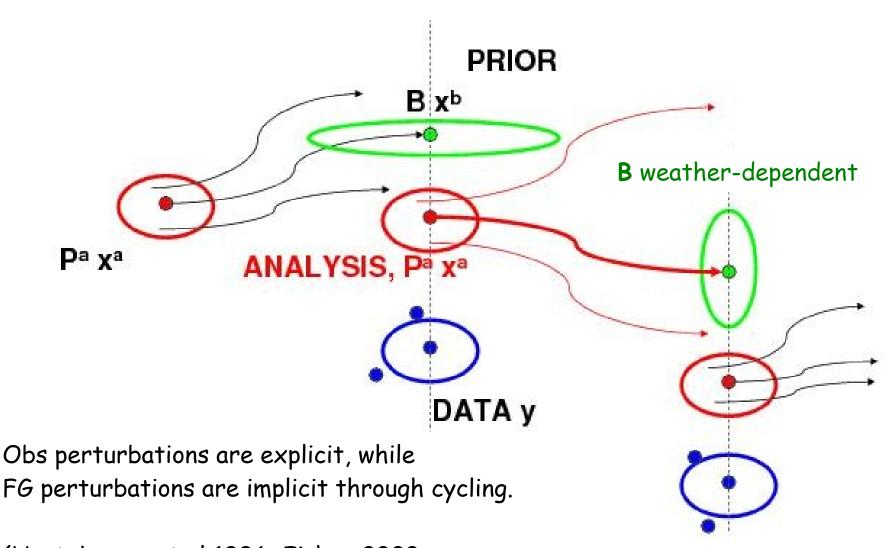
The unperturbed data assimilation cycle and the cycling of errors



Idea is to simulate the error cycling in the reference system through a perturbed assimilation ensemble



Perturbed ensemble data assimilation: simulating the cycling of errors



(Houtekamer et al 1996; Fisher 2003; Ehnandarfan 2006; Panna et al 2006)

Modeling & filtering B: ensemble strategies

There are two « extreme » approaches used to model **B** in variational or EnKF approach.

In Variational: the correlations are usually averaged globally (spatially)

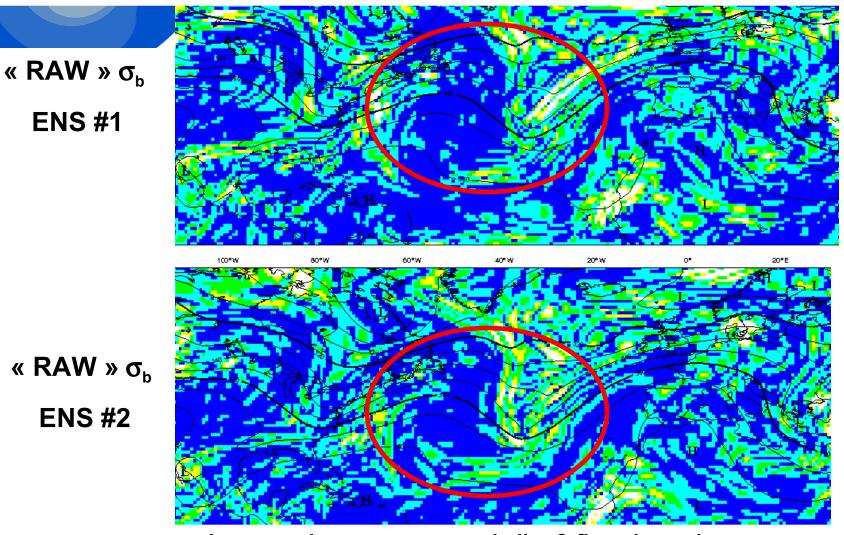
- +: robust even with a very small ensemble
- : does not yield any horizontal heterogeneity

In EnKF: the correlations are purely local (computed at a gridpoint)

- +: Many spatial variations can be represented
- : Requires a large ensemble and ignores the local structure of local covariances
- => **Compromise**: compute local spatial averages of the covariances using a small ensemble which takes the coherent variations of the local covariances into account

"RAW" σ_b (Vorticity, 500 hPa)

from two 3-member ensembles

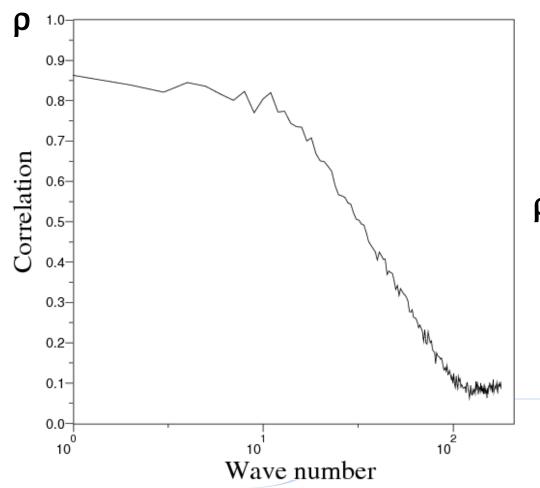


Large-scale structures are similar & flow-dependent

⇒ How do we optimize the estimate, while taking spatial structures into account?

Optimal filtering of the signal

=> Apply the classical Best Linear Unbiased Estimator with a $\,\rho$ filter that takes into account spatial structures of both noise & signal



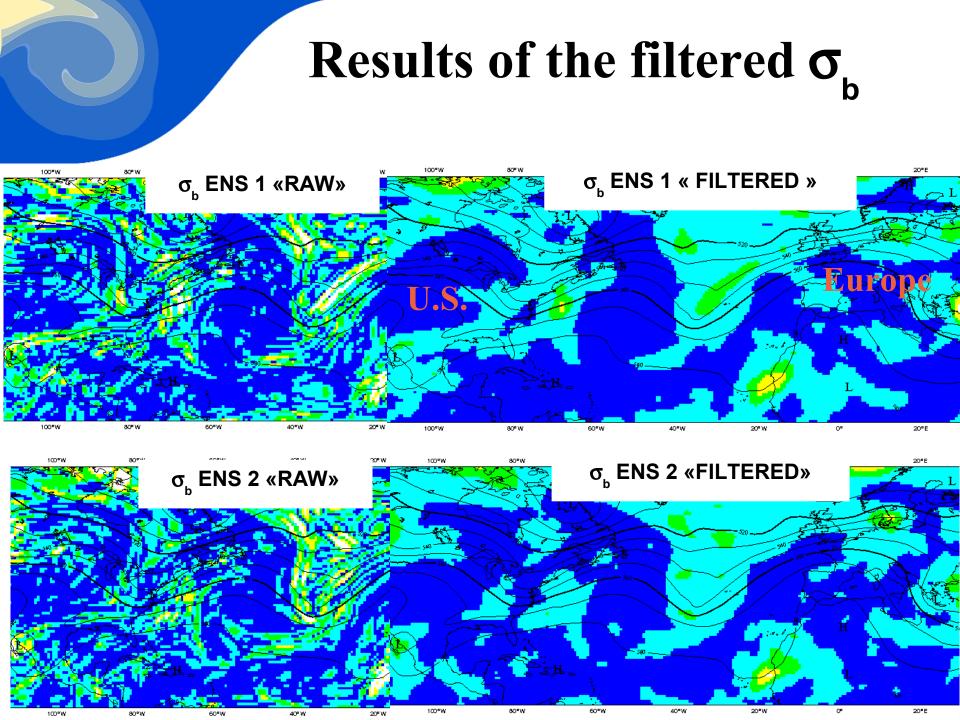
$$\sigma_b^* \sim \rho \sigma_b$$

with

 ρ = signal / (signal+noise)

⇒ρ is a low-pass filter (like K in data assim°).

(Raynaud et al 2008a, 2008b)



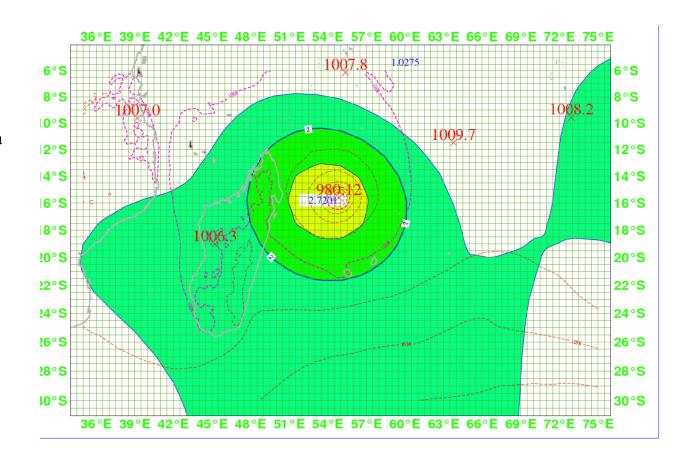
Relation between σ_b "of the day" and a strong meteorological event (TC Ivan, 980 hPa, 15/02/2008, 12UTC)

Color field:

 $\sigma_{_{b}}$ of $\eta_{_{850hPa}}$

Dashed lines:

MSLP



(Montroty, 2008)

=> As one might expect, strong σ_b values are found close the TC center. This holds good potential for impacting the DA.

PART IV: Impacts of those filtered errors on TC forecasting (ongoing)

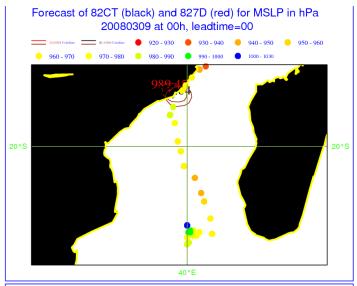


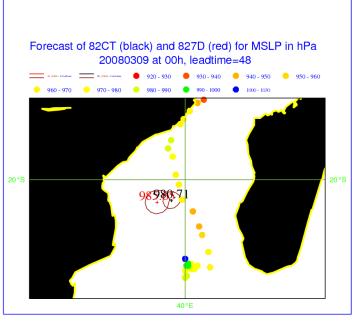
Ensemble assimilation in real-time at Météo France (Loïk Berre)

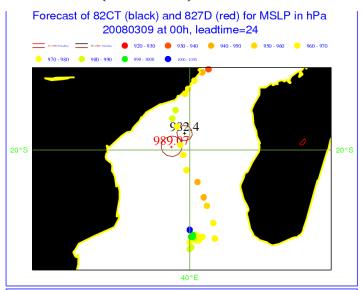
- 6 global and uniform members are run daily at T358C1 L60 with 3D-Fgat (ARPEGE).
- Variances « of the day » are filtered spatially to increase the sample size and the robustness
- The operational suite (4D-Var, T538C2.4 L60) uses those σ_b "of the day » since July 1st, 2008
- The parallel suite was coupled to 6 members of the ALADIN France model (10km) and the next generation model Arome (2.5 km), for 2 seasons of 2 weeks.
- In our studies, we couple ALADIN Reunion to two sets of σ_b coming from two 6-member ensembles: one is the old operational suite equivalent with T42 filtering (FIXED_FILTER), the other one is a refined filtering that is z-dependent and variable-dependent (VARIABLE FILTER) (Raynaud2008b).

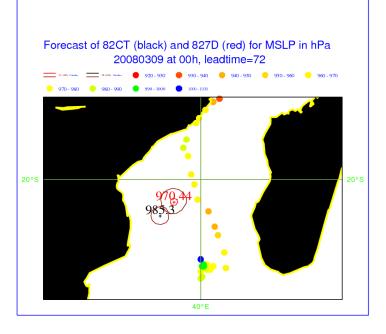


Preliminary results! FIXED_FILTER (red) and VARIABLE FILTER (black)

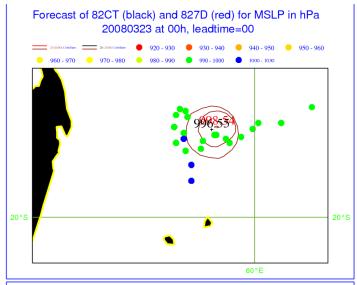


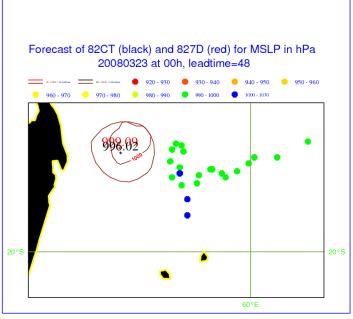


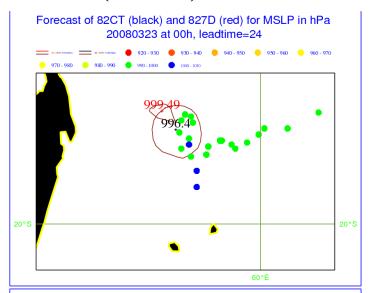


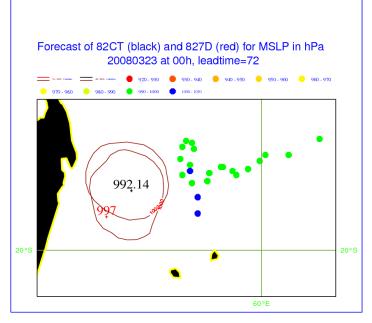


Preliminary results! FIXED_FILTER (red) and VARIABLE_FILTER (black)









PART V: Conclusions



Conclusions (1/2)

- A technique for assimilating SSM/I rainy data was presented through the use of TCWV as an intermediary product: thanks to a multi-linear regression applied to the ECMWF's analyses, a simple algorithm was built to go directly from Tbs to TCWV
- The information contained in this new data is assimilated and improves cyclonic structures in the ALADIN model. Further improvements concern fit to observations and reduced track errors.
- The improved model was downscaled at 4 km: it is found that it reproduces accurately the observed cyclonic signal but a simple dynamical adaptation proves to be too simple in order to accurately position fine structures: 3D-Var assimilation is thus being developed but presents challenging issues at the α -mesoscale level!
- 24h-accumulated precipitation is rather well reproduced in both terms of spatial distribution and intensity



Conclusions (2/2)

- Flow-dependence of background errors is investigated using a 6-member ensemble of a high-resolution, global, uniform ARPEGE model: strong dependence to cyclonic events is found for cyclonic cases which holds great potential for impacting positively the data assimilation scheme.
- Impacts of the filtered background errors on TC forecasting are only beginning to be investigated but, while it seems that intensity might be degraded, track errors seem to be reduced by the use of a z-dependent and variable-dependent filter on the background error covariances.
- The flow-dependent σ_b « of the day » has gone operational on July 1st, 2008 at Météo-France and, in time, the ensemble computation is expected to be transferred to the Ensemble Forecast System (PEARP).



Future Work

The impact studies need to be thoroughly investigated and further computations are needed:

- (1) normalization of the ensemble σ_b fields by ALADIN's statistical level-mean σ_b must be introduced (currently, the normalization is made from the level-mean value contained in the statistical **B** from ARPEGE: a factor 2/3 is expected between the two!)
- (2) Assimilation of all five model variables' error covariances must be implemented (currently, only vorticity and humidity can be assimilated)
- (3) Impact of cloudy/rainy SSM/I data on the most efficient of those system is to be tested. (still in off-line processing)



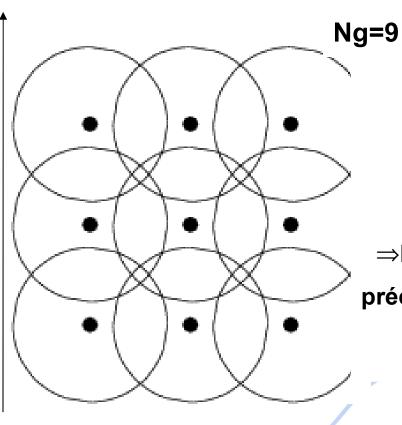
ANNEXES: for curiosity's sake!



AUGMENTATION DE L'ECHANTILLON PAR MOYENNE SPATIALE LOCALE : CONCEPT

Idée: MULTIPLIER(!) la taille d'ensemble Ne par un nombre Ng de points de grille échantillonnés.

latitude



Si Ne=6, alors
la taille totale de l'échantillon est
Ne x Ng = 54.

⇒L'estimation filtrée avec 6 membres est aussi précise qu'une estimation brute avec 54 membres, sous une hypothèse d'homogénéité locale.

longitude

